

# Support properties for SPDE models for spatial branching processes with interaction

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## Continuous state branching

Let  $\psi$  be the Laplace exponent of a spectrally positive Lévy process:

$$\psi(\lambda) = a\lambda + \frac{\sigma^2}{2}\lambda^2 + \int_{(0,\infty)} (\exp^{-\lambda r} - 1 + \lambda r) \nu(dr),$$

where  $a \in \mathbb{R}$ ,  $\sigma \geq 0$ ,  $\int (r \wedge r^2) \nu(dr) < \infty$ .

The  $\psi$ -continuous state branching process (CSBP) is the  $\mathbb{R}_+$ -valued Markov process  $(Z_t)_{t \geq 0}$  with Laplace functional

$$\mathbb{E}_a^Z(e^{-\lambda Z_t}) = e^{-au_\lambda(t)},$$

where  $u_\lambda(t)$  solves the evolution equation

$$\dot{u}_\lambda(t) = -\psi(u_\lambda(t)), \quad u_\lambda(0) = \lambda.$$

## Super-Brownian motion

A  $\psi$ -super-Brownian motion is the  $\mathcal{M}_f(\mathbb{R}^d)$  (measure)-valued process  $(X_t)_{t \geq 0}$  with Laplace functional

$$\mathbb{E}_{X_0}^X(e^{-\langle X_t, \phi \rangle}) = e^{-\langle X_0, v_\phi(t, \cdot) \rangle},$$

where  $v_\phi(t)$  satisfies the PDE

$$\dot{v}_\phi(t, x) = \frac{1}{2} \Delta v_\phi(t, x) - \psi(v_\phi(t, x)), \quad v_\phi(0, x) = \phi(x).$$

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The cases  $\psi(u) = u^2$  and  $\psi(u) = u^\alpha$ ,  $\alpha \in (0, 2)$ , correspond respectively to binary and  $\alpha$ -stable branching.

(If  $\alpha \in (1, 2)$ , we typically write  $\alpha = 1 + \beta$ ,  $\beta \in (0, 1)$ .)

# The compact support property

Fact: for  $\psi(u) = u^2$  and  $\psi(u) = u^\alpha$ ,  $\alpha \in (1, 2)$ , the  $\psi$ -super-Brownian motion  $X_t$  satisfies the **compact support property**:

If  $X_0$  has compact support,

$\overline{\bigcup_{s \in [0, t]} \text{supp}(X_s)}$  is compact for all  $t > 0$  a.s.

## CSBP and SDE

Lamperti transform: the  $\psi$ -CSBP is the Lévy process with characteristic exponent  $\psi$  time-changed to run at speed equal to its size.

Suppose that  $\psi$  is the branching mechanism of a pure jump CSBP with Lévy measure  $\nu$ . Let  $N(dr, dz, ds)$  be a compensated Poisson random measure with intensity  $\nu(dr)dzds$ . We may then write

$$Z_t - Z_0 = \int_0^t \int_0^{Z_{s-}} \int_0^\infty rN(dr, dz, ds).$$

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## CSBP and SDE

If  $\psi(u) = u^\alpha$ , then  $\nu(dr) = c_\alpha r^{-1-\alpha}$ , and a scaling calculation shows that the following processes are equal in law:

$$\int_0^t \int_0^{Z_{s-}} \int_0^\infty r N(dr, dz, ds) \quad \text{and} \quad \int_0^t \int_0^1 \int_0^\infty (Z_{s-}^{1/\alpha} r) N(dr, dz, ds).$$

In particular,  $Z_t$  satisfies the jump SDE

$$dZ_t = Z_{t-}^{1/\alpha} dW_t,$$

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The CSBP associated to  $\psi(u) = u^2$  is Feller's branching diffusion

$$dZ_t = Z_t^{1/2} dB_t.$$

## Super-Brownian motion and SPDE

Similarly, for  $\psi(u) = u^2$ , the density of  $\psi$ -super-Brownian motion in  $d = 1$  satisfies

$$\partial_t X(t, x) = \frac{1}{2} \Delta X(t, x) + X(t, x)^{1/2} \dot{\xi}_2(t, x), \quad t > 0, x \in \mathbb{R}.$$

where  $\dot{\xi}_2$  is space-time white Gaussian noise.

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where  $\dot{\xi}_2$  is space-time white Gaussian noise.

For  $\psi(u) = u^\alpha$ , the density of  $\psi$ -super-Brownian motion for  $d < \frac{2}{\alpha-1}$  satisfies

$$\partial_t X(t, x) = \frac{1}{2} \Delta X(t, x) + X(t, x)^{1/\alpha} \dot{\xi}_\alpha(t, x), \quad t > 0, x \in \mathbb{R}^d.$$

where  $\dot{\xi}_\alpha$  is space-time white (spectrally positive)  $\alpha$ -stable noise.

## State-dependent branch rates

In a *non-linear CSBP*, the branch rate is a function of the total population size: for some increasing  $R : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ ,

$$Z_t - Z_0 = \int_0^t \int_0^{R(Z_{s-})} \int_0^\infty r N(dr, dz, ds).$$

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In the Brownian and stable cases, we respectively have

$$dZ_t = R(Z_t)^{1/2} dB_t$$

and

$$dZ_t = R(Z_{t-})^{1/\alpha} dW_t.$$

## Density-dependent branch rates

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$$\partial_t X(t, x) = \frac{1}{2} \Delta X(t, x) + X(t, x)^\gamma \dot{\xi}_\alpha(t, x), \quad t > 0, x \in \mathbb{R}^d$$

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Decompose noise term as

$$X(t, x)^\gamma \dot{\xi}(t, x) = \underbrace{X(t, x)^{\gamma - \frac{1}{\alpha}}}_{\text{variable branch rate}} \times \underbrace{X(t, x)^{\frac{1}{\alpha}} \dot{\xi}(t, x)}_{\alpha\text{-stable branching}}$$



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For what values of  $\gamma$  does  $X(t, \cdot)$  have compact support?

## Compact support - Gaussian noise.

Let  $\alpha = 2$ . (Gaussian noise;  $d = 1$ .) Consider a non-negative solution to

$$\partial_t X(t, x) = \frac{1}{2} \Delta X(t, x) + X(t, x)^\gamma \dot{\xi}_2(t, x), \quad t > 0, x \in \mathbb{R}.$$

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Theorem (Shiga 1994; Mueller & Perkins, 1992; Krylov, 1997)

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- If  $\gamma < 1$ ,  $X$  has the compact support property.

Theorem (Mueller, 1990)

- If  $\gamma \geq 1$ ,  $X(t, x) > 0$  for all  $t > 0, x \in \mathbb{R}$ .

## Compact support - stable noise (main result)

Let  $\alpha \in (1, 2)$ . ( $\alpha$ -stable noise;  $d < \frac{2}{\alpha-1}$ .) Consider a non-negative solution to

$$\partial_t X(t, x) = \frac{1}{2} \Delta X(t, x) + X(t, x)^\gamma \dot{\xi}_\alpha(t, x), \quad t > 0, x \in \mathbb{R}^d.$$

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Theorem (H. 2022+)

- ( $d = 1$ ) If  $2 - \alpha < \gamma < 1$ ,  $X$  has the compact support property.
- ( $d > 1$ ) If  $1/\alpha \leq \gamma < 1$ ,  $X$  has the compact support property.

## Elements of the proof

The proof uses the method of Krylov.

First let  $d = 1$ . Suppose  $\text{supp}(X_0) \subset (-R, R)$ . Mass moves continuously by diffusion, so if  $X_t([R, \infty)) > 0$ , we must have  $A_t(R) > 0$ , where

$$A_t(x) = \int_0^t X(s, x) ds.$$

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Integration by parts gives

$$\int_x^\infty (y - x) Y_t(y) dy = A_t(x) + \int_{(0,t] \times \mathbb{R}} (y - x)_+ Y_s(y) \gamma \xi(ds, dy).$$



## Elements of the proof

Use the IBP formula to obtain estimates of the following form: for  $x_1 \approx x_0 + r$ ,

$$\mathbb{P}(A_t(x_1) \geq a) \leq \mathbb{P}(A_t(x_0) \geq b) + \text{Error}(a, b, t, r).$$

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Iterating this estimate for a good choice of parameters, one obtains, for some  $L > 0$ ,

$$\mathbb{P}(A_t(x + L) > 0) \leq \mathbb{P}(A_t(x) > \epsilon) + O(\epsilon).$$

Taking  $x \rightarrow \infty$  and  $\epsilon \rightarrow 0$ , conclude that

$$\lim_{x \rightarrow \infty} \mathbb{P}(A_t(x) > 0) = 0.$$

## Elements of the proof; other remarks

For  $d > 1$ : the occupation density  $A_t(x)$  is replaced with the occupation density along a  $(d - 1)$ -dimensional hyperplane or sphere. Some complexities arise.

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It is supposed to be easy for small  $\gamma$  - what goes wrong?

## A result on explosions

Concerning blow-up, consider the following theorem: let  $X$  be a non-negative solution to

$$\partial_t X(t, x) = \frac{1}{2} \Delta X(t, x) + X(t, x)^\gamma \dot{\xi}_2(t, x), \quad t > 0, x \in \mathbb{R}.$$

Theorem (Mueller, 2000)

If  $\gamma > 3/2$ ,  $\|X_t\|_\infty \rightarrow \infty$  in finite time a.s.

Thank you!